

TM AI COBOT

The future is here,

TM AI COBOT

Native AI engine + Robotic arm + Vision system

(All in ONE)











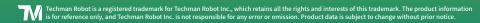










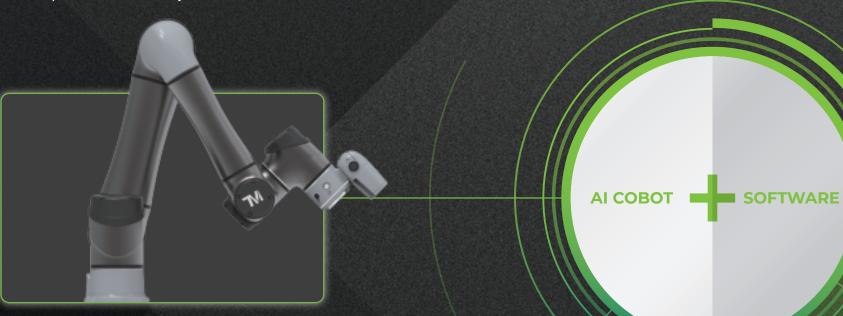


What Is An AI Cobot?

TM Al Cobot **S** Series

Al Cobot is a collaborative robot that seamlessly blends three technological domains together - Al, Vision, and Cobot. This integration effectively combines the functions of a 'brain,' 'eyes,' and 'hands,' enabling the cobot to perform visual tasks, making judgments, and executing actions much like a human. Automating processes not only saves time and resources but also promotes effective human-robot collaboration, enhancing overall production quality, and adds a significant value to your factory.

Fifteen years ago, collaborative robots introduced the concept of humans and robots working together. Today, the new generation of AI collaborative robots has turned the dream of having intelligent and reliable partners into a reality.



Al Model Training Platform

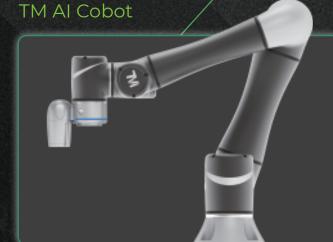


TM Al+™ Trainer

Inspection Image Management



TM Image Manager



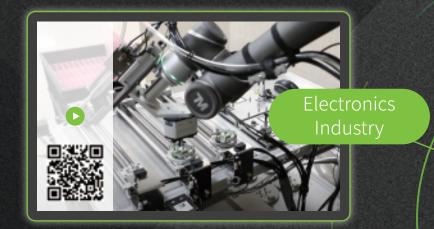
Vision Inspection Software



TM AI+™ AOI Edge

Industry Applications

TM AI Cobot offers exceptional performance and compatibility. Equipped with a built-in vision system, it enables the robot to perceive its surroundings. Its AI brain also translates image data into precise commands for tasks such as positioning and detection, seamlessly integrating with the robot arm to execute tasks efficiently. In the era of AI, **TM AI Cobot** is the best choice to for realizing smart factories.

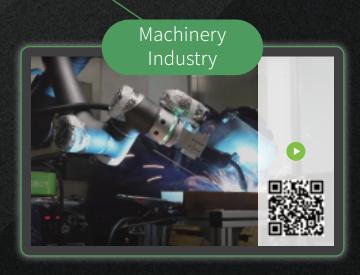










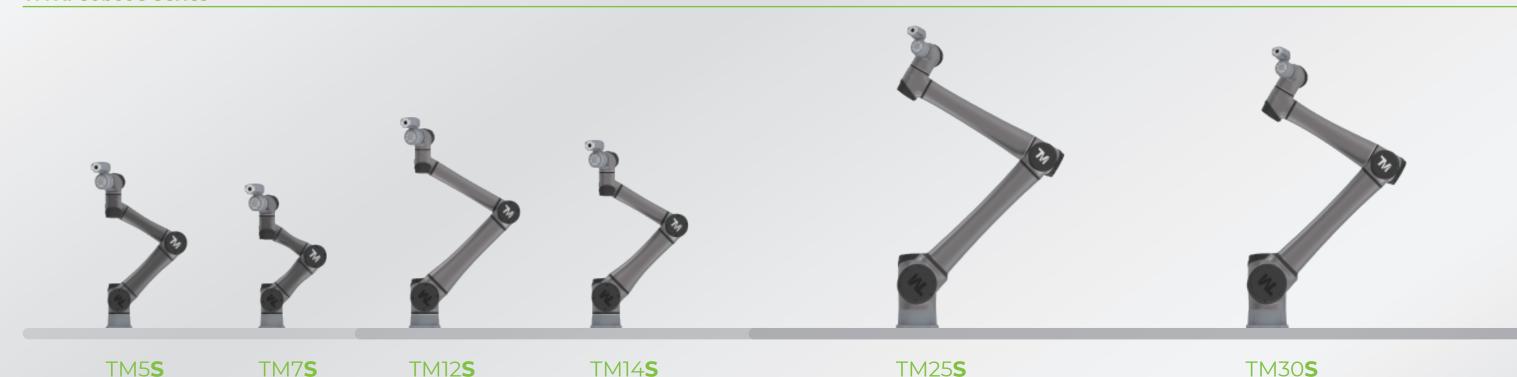


Introducing TM AI Cobot

The only AI-powered collaborative robot with advanced vision capabilities

TM AI Cobot

TM AI Cobot S Series



TM AI Cobot Series

5 kg

946 mm

Payload |

Reach |



Payload |

Reach

6 kg 746 mm

7 kg

758 mm

4 kg 946 mm 12 kg 1300 mm

12 kg

1300 mm

14 kg 1100 mm

14 kg

1100 mm

16 kg 917 mm

20 kg 1300 mm

25 kg

1902 mm

+ Additional Types

35 kg*

1702 mm

TM Mobile Series

TM Mobile Series cobots can be integrated with almost all AGV/AMR brands on the market. With its embedded vision and TM Landmark vision function, the mobile series is extremely suitable for applications and tasks that require mobility. Such as machine tending or palletizing.

No Built-in Vision Robot Series

TM Robot Series offers robot arms with no built-in vision for users who want to integrate external cameras by themselves. Feel free to check on the pre-verified list of cameras from our TM Plug&Play™ series to save time on finding a compatible camera.

*Under the palletizing scenario

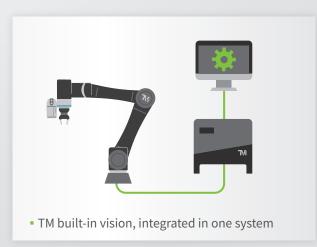
Introducing TM AI Cobot

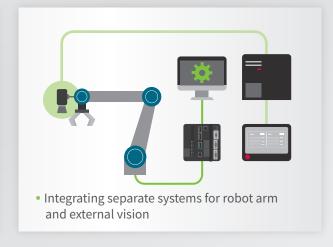
The only AI-powered collaborative robot with advanced vision capabilities

SMART

A perfect integration of cobot and machine vision

- Hand and eye integration for time/labor-saving solution
- Powerful vision function: The combination of traditional machine vision and AI vision offers the user a comprehensive vision function including vision positioning, measurement, defect inspection, OCR and barcode reading
- Easily manage both robot arm and vision functions within a single software, eliminating the need to learn two separate programs and concerns about system compatibility or interface issues





	TM built-in vision	Robot arm + External vision
Camera	All-in-one	Requires additional mechanism for integration
Camera signal cable and power cord	Internally routed cables	Externally routed cables can lead to problems like tangled or pulled cables or dust resulted from friction
Vision recognition system	5M color camera, auto focus, built-in light source, various applications	Complicated configuration of lens, camera, light source and software
Vision and Robot Programming	Integrated in one software TMflow™ for easy programming	Need to handle the communication interface of 2 different software
Charge	The cost of the robot arm includes the vision system	Additional charge of vision software /hardware is required

A plug-and-play 3D vision solution requires no additional software/hardware integration

When incoming materials are stacked or arranged in different configurations, the positioning function may become ineffective or less accurate due to the limitations of a standard robot's 2D vision, which cannot capture 3D coordinates. To overcome this challenge, Techman Robot has introduced TM 3DVision™, a 3D machine vision solution with paried designated Plug&Play 3D camera, designed to expand the range of items recognizable by the vision system and enhance the precision of both vision-based positioning and arm movement.





Traditional Solution

Requires more time and labor costs to integrate robot arm, 3D camera, and software from different brands

All-In-one Solution

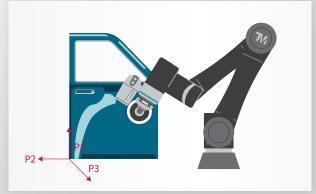
Significantly reduces integration costs and efforts, maintenance and accountability issues

Features

- The integration of 3D software and TMflow™ interface achieves high integration and easy operation
- No additional vision controller is required. No need for complicated system handshaking settings
- Can be used with the collision check function and prevent any potential collision risks.
 This is highly recommended for the Random Bin Picking applications.



Picking up scattered materials



Single item 3D positioning

Introducing TM AI Cobot

The only Al-powered collaborative robot with advanced vision capabilities

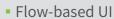
SIMPLE

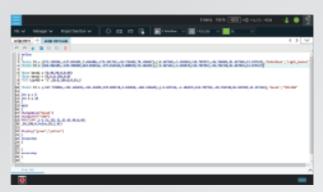
More Freedom to Program the Cobot

TMflow™ is a user-friendly software that allows you to create and edit robot tasks through a graphical interface using a series of function nodes, making it easy for first-time users to learn our flow-based programming without any robotics experience.

If you prefer non-graphical programming, experience a more flexible way to program by using the new Script Node and Script Project. The Script feature allows experienced engineers to program with complex logic, and freely edit robot tasks by compiling codes. Embrace the method that suits you best and enjoy coding with unparalleled freedom!







Script for Complex Logical Programming

Create Personalized Interface with TMcraft for 2nd Development

TMcraft is a new architecture that allows you to create your own customized UI or background program and embed it onto TMflow™, our cobot programming software. It offers the freedom to develop third-party plug-and-play applications using C# and WPF development. Additionally, a wizard is available to facilitate the development of high-level applications, such as welding, palletizing, and sanding, making it easier to customize and create the applications you need.

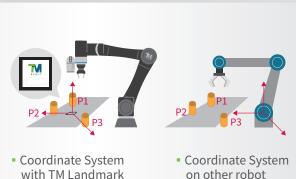


 Developers can develop nodes in their own environment



Embed into TMflow[™] using third-party plugins

Built-in vision with one-click positioning



on other robot

TM Landmark

General robot has the coordinate system built on its base, when the relative position between the objects and the robot changes, the robot require re-adjustment. With TM Landmark, the coordinate system is built on the landmark, the robot will only need to scan the landmark and the coordinate info can be updated without re-adjustment. This is especially recommended to robot with AGV!

Visual Calibration

TM Calibration board can largely reduce the complexity of visual calibration process. Whether users are using EIH, ETH or Upwardlooking camera, just simply place the calibration board under the camera, press the button and TMvision™ will do all the work!

Built-in vision application





Eve-in-Hand







Eye-to-Hand Upward-looking Conveyor Tracking

Identification



Barcode/

QR code Reading









Distance and Angle

Measurement

Caliper



Count (Edge)





Classification

Object Detection



Semantic egmentation



Anomaly Detection



Segmentation

Al Vision Software

Powering the future of factories with AI power



Completely integrate hands, eyes and brain in automation field

TM Al+™ Trainer is a software tool that will help you manage image data, set up Al training parameters, and train AI models. The AI solution can help you train a model that fits your needs effortlessly. This AI model can be applied to both the robot arm and machine vision, thus forming a powerful combination of the arm(cobot), eye(machine vision), and brain(AI). Easy and simple UI helps the user to rapidly and conveniently introduce AI vision technology to production. Al incorporating vision system can effectively eliminate quality issues resulted from fatigue or human error.

Features

- A graphical interface that is easy to learn
- Designed as a browser-based software that you can log in anywhere with a web browser
- All image data used for AI model training is stored in a local database to ensure enterprise classified data is secure
- Powerful AI Vision technology with capabilities including anomaly detection, classification, object detection, and semantic segmentation

4 steps for easy AI model training

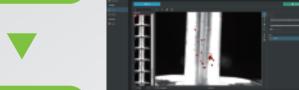
Image collection



Collect Image Data

 Take multiple photos of the object and upload them to TM AI+™ Trainer

Annotation



TM AI+™ Trainer

- Select the type of vision task: Classification, Detection, Segmentation, Anomaly Detection
- Label the uploaded image samples
- Configure training parameters and begin training
- Evaluate the training outcome

Training



Import AI model

- Download the trained AI model from the TM AI+™ Trainer to TM Robot or external camera
- Begin Al inference

TM Image Manager

Comprehensive quality traceability for your product

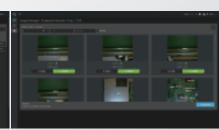
After an enterprise sells its product to customers, they often must deal with customer feedback or complaints. Therefore, companies need to establish a comprehensive quality traceability system. TM Image Manager is a software tool that is highly compatible with the vision function of TM Al Cobot. It can help you effectively manage the quality inspection records of each product. The inspector can monitor the inspection progress in real time and the results are automatically recorded as image data. This data can be reviewed at any time to increase inspection accuracy. Furthermore, a quality resume can be improved and the potential cost of after-sales service activities can be reduced.

Features

- Browser-based interface for intuitive and easy operation
- Manage inspection images and results through the database to address the needs of backup and search
- The user can filter the images of quality inspection by different conditions, like time, work order, barcode, etc. at any time
- Help inspectors to compare the images of inspection and standard item to effectively reduce the probability of misjudgement
- The user can plan and design inspection configuration to perform real-time monitoring on inspection position, result and progress



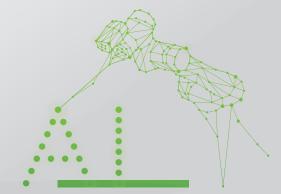




 Configuration inspection and progress review

 Backup and search of inspection history

 Support human double-check interface

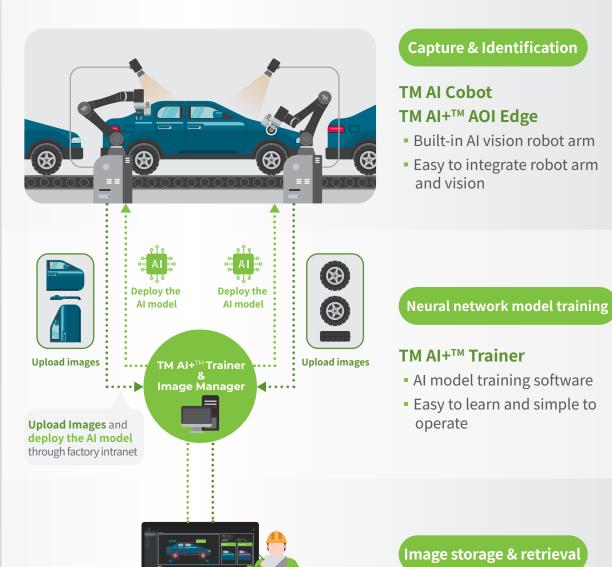


Al Vision Software

Powering the future of factories with AI power

AI Vision Operating Architecture

The graphical interface of TM AI Cobot's integrated vision system eliminates the need for programming and enables a seamless process from image collection and annotation to training and deployment. It serves as an ideal solution for small and medium-sized enterprises (SMEs) lacking an AI or software division. Throughout production, AI Cobot accumulates valuable production history data, empowering companies to track, analyze, and integrate this information to proactively prevent defects, enhance quality, and reduce costs.



Application Examples

Assembly Inspection





• Checking if the tires are wrapped with PE film



• Checking if all wires are connected correctly



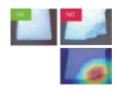


 Sorting different materials for wooden furniture



 Recognition of pizza flavor and crust

Defects Inspection



 Identifying objects with damage on the edge



• Checking if there are metal scrap on the surface



AI OCR



• Counting the amount of the object in the tray



 Objects detection and 3D positioning



Execute Al training, review, and image retrieval through browser

TM Image Manager

- AOI image management software
- Backup all AOI inspection images and establish product traceability



 Checking scratches on DRAM gold fingers



• Checking the dents on metal parts



Label text reading



Label text reading

TM Plug&PlayTM Solution

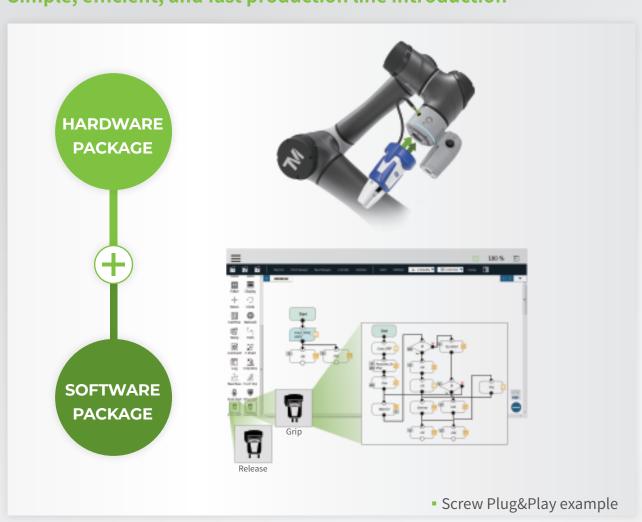
TM certified, perfect integration, and usable upon installation

TM AI Cobot works with peripheral equipment vendors to create a comprehensive TM Plug&Play™ ecosystem. Each certified TM Plug&Play™ product has been calibrated and tested by Techman Robot and peripheral equipment vendors. This ensures users benefit from an optimal experience and highly reliable robot performance, while significantly reducing the time and labor costs associated with hardware production and automation programming.

Start to use within 5 minutes



Simple, efficient, and fast production line introduction



TMPlug&Play[▶]

CERTIFIED



AIR-3002022



ARS Automation FlexiBowl® Kit for TM



ARH350A Kit for TM



9105-TM-Axia80



Industrial Camera



RCKL/RHLF/RLSH -TM Gripper



COBOTRACKS Linear Motion Plug&Play for TM



DH-Robotics Adaptive Gripper DH-3 TM Kit



EWELLIX

LIFTKIT-TM

ACF-K Active Contact Flange-Kit



Industrial Camera



KIT-TM-J



Electric Gripper X-series



Ensenso N36/N46



3D e-chain TM Kit - PMA Tubes Screw Driver Solution



KILEWS



All-in-One Gripper Murrplastik FHS-SH-Set for TM Robot (3-Finger)



NABELL Robot Flex



NITTOSEIKO Pick and Drive System







OnRobot Screwdriver



Pickit3D Vision Solution



RoboDK Simulation and Offline **Programming Software**



FTS-300-TM-KIT



Adaptive Gripper, 2-Finger 85/140 TM Kit



Schmalz FXCB



Changing by SCHUNK
- Plug & Work Portfolio
Techman Robot



Collaborative gripping EGP-C



Magnet Gripper Unit



CHY2B-S80



GRIPKIT-CR-PRO-L



Zimmer HRC-03 TM-Kit



Universal Mobile Stand



TM AI Cobot S Series Specification

			Specificati	on								
М	odel	TM5S	TM7S	TM5S-M	TM7S-M	TM5S-X	TM7S-X					
W	eight	23.9kg	22.9kg	23.9kg	22.9kg	23.6kg	22.6kg					
Maximum Payload		5kg	7kg	5kg	7kg	5kg	7kg					
Reach		946nn	758nn	946mm	758mm	946mm	758nn					
Joint Ranges	J1, J2, J4, J5, J6			+/- 360*								
	J3	+/- 158°	+/- 152*	+/- 158°	+/- 152"	+/- 158°	+/- 152					
	J1, J2			210°/s		1						
	J3			210°/s								
Speed	J4			225°/s								
	J5	225*/s										
	J6	450°/s										
Max.	. Speed			4.5m/s								
Repe	atability			+/- 0.03mm								
Degree (Of Freedom			6 rotating joi	nts							
	Control Box			Digital In: 16 / Digit	al Out: 16							
1/0	Control Box			Analog In: 2 / Analog	og Out: 2							
1/0	T-10			Digital In: 3 / Digit	al Out: 3							
	Tool Conn.	DO_0 (DO-0/AI) / DO_1 (DO-1/RS485-) / DO_2 (DO-2/RS485+)										
I/O Pow	er Supply		24V	2.0A for control box, 2	24V 1.5A for tool							
ID Cl.			IP54 (Robot Arm) IP54 (Robot Arm)			IP54 (Robot Arm)						
IP Classification		IP54 (Control Box)				IP54 (Co	ntrol Box)					
Typical Power Consumption		240W										
Temperature		0~50°C										
Clea	nliness	ISO Class 3										
Powe	r Supply	100~240 VAC, 50~60 Hz 24~60 VDC 100~240 VAC, 50~60 Hz										
I/0 Ir	nterface	2×COM, 1×HDMI, 3×LAN, 2×USB2.0, 4×USB3.0										
£		RS-232/RS-422/RS-485, Ethernet, Modbus TCP/RTU (master & slave)										
Comm	unication	PROFINET (optional), EtherNet/IP (optional)										
Programmin	g Environment	TMflow (flowchart), TMscript (script based), TMcraft (development program)										
		TÜV certificated ISO 13849-1, ISO 10218-1, ISO/TS 15066										
Certi	fication	SGS certificated UL1740, CAN/CSA Z424-14 (R2019)										
		CE, SEMI S2 (optional)										
			AI & Robot Vi	sion								
Al Fu	unction	Classification, Object Detection, Segmentation, Anomaly Detection, AI OCR										
Application		Positioning, 1D/2D Barcode Reading, OCR,										
иррі	Application		Defect Detection, Measurement, Assembly Check									
		2D Positioning: 0.1 mm *(1)										
Positioni	ng Accuracy	TM Landmark 3D positioning (the working point is located 100/200/300mm										
		away from the landmark): 0.10/ 0.20/ 0.33 mm *(1)										
Eye in Ha	nd (Built in)	Auto-focused color camera with 5M resolution, Working distance 100 mm ~ ∞										
Eye to Har	nd (Optional)	Supp	ort Maximum 2× Gi	gE 2D cameras or 1×	GigE 2D Camera + 1	LX 3D Camera * ⁽²	0					

^{*(1)} The data in this table are measured by TM laboratory and the working distance is 100mm. It should be noted that in practical applications, the relevant values may be different due to factors such as the on-site ambient light source, object characteristics, and vision programming methods that will affect the change in accuracy.



					Specif	ication						
TM12S	TM14S	TM25S	TM30S	TM12S-M	TM14S-M	TM25S-M	TM30S-M	TM12S-X	TM14S-X	TM25S-X	TM30S-	
33.3kg	33kg	81.6kg	80.6kg	33.3kg	33kg	81.6kg	80.6kg	33kg	32.7kg	81.3kg	80.3kg	
12kg	14kg	25kg	30kg	12kg	14kg	25kg	30kg	12kg	14kg	25kg	30kg	
1300nn	1100mm	1902mm	1702mm	1300nm	1100mm	1902mm	1702mm	1300nm	1100nn	1902mm	1702m	
					+/-:	360°						
+/- 162°	+/- 159°	+/- 166°	+/- 170°	+/- 162°	+/- 159°	+/- 166°	+/- 170*	+/- 162°	+/- 159°	+/- 166° +/- 17		
)°/s)°/s)°/s)°/s		130°/s		100°/s	
210)*/s)°/s)*/s)*/s)*/s	
225		195			5°/s		5°/s		5°/s		5°/s	
225		210			5°/s)°/s		o°/s)°/s	
)°/s	225)°/s		5°/s)°/s		i"/s	
	inβ	5.2			injs	5.7	2m/s		injs		čm/s	
+/- 0.	.03nn	+/- D.	.05nn	+/-0	.03nn		.05nn	+/-0	.03nn	+/- 0.	.05mm	
						ng joints						
					Digital In: 16/							
					Analog In: 2 /							
					Digital In: 3 /							
			DO		DO_1 (DO-1/			15+)				
				24V 2.0	A for control		for tool					
IP54 (Robot Arm) IP54 (Robot Arm) IP54 (Robot Arm)												
IP54 (Control Box) IP54 (Control Box)												
40	00W 600W 400W 600W 400W 600W							OW				
100-010-0	c 50-60 ii-	202-240-0	c 50-60 u-	24.6		lass 3	W. m.c	100-240	c 50-60	200. 240	- E0-60 II-	
100~240 W	c, 50~60 Hz	200~240 W	c, 50~60 Hz	24~60 vpc 48~60 vpc 2×COM, 1×HDMI, 3×LAN, 2×USB2.0, 4×USB3.0				100~240 W	с, 50~60 нг	200~240 VA	C, 50~60 Hz	
			DC 222				-	h -1h				
			K5-232		85, Ethernet,			s slave)				
			T140 /D -		T (optional),							
					cript (script ba							
					d ISO 13849-1 ated UL1740,			10				
				ada certific			4-14 (KS013)					
						2 (optional) ot Vision						
					ru ei ROD	OT AIRIOH						
	Classificati	ion, Object De	tection, Segn	nentation, An	omaly Detect	ion, AI OCR						
		Position	ning, 1D/2D B	arcode Readir	ng, OCR,							
			-	rement, Asse	_							
				g: 0.1 mm * ⁽¹⁾					N	/A		
	TM Landm			*		00/300mm						
TM Landmark 3D positioning (the working point is located 100/200/300mm away from the landmark): 0.10/ 0.20/ 0.33 mm *(1)												
		away from	the landmark	l- 0.10/ 0.20/	0.33 mm * ¹¹							

^{*(1)} The data in this table are measured by TM laboratory and the working distance is 100mm. It should be noted that in practical applications, the relevant values may be different due to factors such as the on-site ambient light source, object characteristics, and vision programming methods that will affect the change in accuracy.

Support Maximum 2× GigE 2D cameras or 1× GigE 2D Camera + 1× 3D Camera *12)

^{*(2)} Refer to the official website of TM Plug&Play for camera models compatible to TM Robot.

^{*(2)} Refer to the official website of TM Plug&Play for camera models compatible to TM Robot.

TM AI Cobot Specification

			Specificati	on								
М	lodel	TM5-700	TM5-900	TM5M-700	TM5M-900	TM5X-700	TM5X-900					
W	eight	22.1kg	22.6kg	22.1kg	22.6kg	21.8kg	22.3kg					
Maximum Payload		6kg	4kg	6kg	4kg	6kg	4kg					
Reach		746mm	946mm	746mm	946mm	746mm	946mm					
	J1,J6	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 360°	+/- 360°					
Joint Ranges	J2,J4,J5	+/- 180°	+/- 180*	+/- 180°	+/- 180°	+/- 360°	+/- 360°					
	J3		+/- 155°									
	J1,J2			180°/s								
	J3			180°/s								
Speed	J4			225*/s								
	J5	225°/s										
	J6	225°/s										
Max	. Speed			4m/s								
Repe	atability			+/- 0.05mn	n							
Degree (Of Freedom			6 rotating joi	nts							
	Control Box			Digital In: 16 / Digit	al Out: 16							
1/0	Control Box	Analog In: 2 / Analog Out: 1										
1/0	Tool Conn	Digital In: 4 / Digital Out: 4										
	Tool Conn.	Analog In: 1 / Analog Out: 0										
I/O Power Supply		24V 2.0A for control box, 24V 1.5A for tool										
IP Classification		IP54 (Robot Arm)										
		IP32 (Control Box)										
Typical Power Consumption				220W								
Temp	perature	0-50°C										
Clea	nliness	ISO Class 3										
Powe	r Supply	100-240 VAC, 50-60 Hz 22-60 VDC 100-240 VAC, 5										
I/0 Ir	nterface	3×COM, 1×HDMI, 3×LAN, 4×USB2.0, 2×USB3.0										
Comm	unication	RS-232, Ethernet, Modbus TCP/RTU (master & slave)										
Commi	anication	PROFINET (optional), EtherNet/IP (optional)										
Programmir	ng Environment	TMflow (flowchart), TMscript (script based), TMcraft (development program)										
Certi	fication	ISO 13849-1, ISO 10218-1, ISO/TS 15066										
CCIT	incation.	CE, SEMI S2 (optional)										
			Al & Robot Vi	sion								
Al Fo	unction	Classification, Object Detection, Segmentation, Anomaly Detection, AI OCR										
Application		Positioning, 1D/2D Barcode Reading, OCR,										
Арр	Application		Defect Detection, Measurement, Assembly Check									
			2D Positioning: 0.1 mm *(1)									
Positioni	ng Accuracy	TM Landmark 3D positioning (the working point is located 100/200/300mm										
		away from the landmark): 0.24/ 0.53/ 1.00 mm *(1)										
Eye in Ha	ınd (Built in)	Auto-focused color camera with 5M resolution, Working distance 100 mm ~ ∞										
Eye to Har	nd (Optional)	Supp	ort Maximum 2× Gi	gE 2D cameras or 1×	GigE 2D Camera + 1	× 3D Camera * ⁽²)					

^{*(1)} The data in this table are measured by TM laboratory and the working distance is 100mm. It should be noted that in practical applications, the relevant values may be different due to factors such as the on-site ambient light source, object characteristics, and vision programming methods that will affect the change in accuracy.



Specification											
TM12	TM14	TM16	TM20	TM12M	TM14M	TM16M	TM20M	TM12X	TM14X	TM16X	TM20X
32.8kg	32.5kg	32kg	32.8kg	32.8kg	32.5kg	32kg	32.8kg	32.5kg	32.2kg	31.7kg	32.5kg
12kg	14kg	16kg	20kg	12kg	14kg	16kg	20kg	12kg	14kg	16kg	20kg
1300mm	1100mm	917mm	1300mm	1300mm	1100mm	917mm	1300mm	1300mm	1100mm	917mm	1300mr
+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 360°	+/- 360°	+/- 360°	+/- 360
+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 180*	+/- 360°	+/- 360°	+/- 360°	+/- 360
+/- 166"	+/- 163°	+/- 155°	+/- 166°	+/- 166°	+/- 163*	+/- 155°	+/- 166*	+/- 166°	+/- 163*	+/- 155°	+/- 166
120°/s	120°/s	120°/s	90°/s	120°/s	120°/s	120°/s	90°/s	120°/s	120°/s	120°/s	90°/s
180°/s	180°/s	180°/s	120°/s	180°/s	180°/s	180°/s	120°/s	180°/s	180°/s	180°/s	120°/s
180°/s	150°/s	180°/s	150°/s	180°/s	150°/s	180°/s	150°/s	180°/s	150°/s	180°/s	150°/s
180°/s	150°/s	180°/s	180°/s	180°/s	150°/s	180°/s	180°/s	180°/s	150°/s	180°/s	180°/s
180°/s	180°/s	180°/s	225°/s	180°/s	180°/s	180°/s	225°/s	180°/s	180°/s	180°/s	225°/s
					4n	1/s					
					+/- ().	1mm					
					6 rotatir	ng joints					
]	Digital In: 16 /	Digital Out: 1	6				
					Analog In: 2 /	Analog Out: 1	l				
					Digital In: 4 /	Digital Out: 4					
					Analog In: 1/	Analog Out: ()				
				24V 2.0	A for control l	юх, 24V 1.5A	for tool				
					IP54 (Ro	bot Arm)					
					IP32 (Cor	ntrol Box)					
					30	OW					
					0-5	0°C					
					ISO C	lass 3					
100-240 VAC, 50-60 Hz 22-60 VDC 24-60 VDC 100-240 VAC, 50-60 Hz											
				3×COM,1>	×HDMI,3×LA	N, 4×USB2.0	,2×USB3.0				
				RS-232, Ethe	rnet, Modbus	TCP/RTU (ma	aster & slave)				
				PROFINE	T (optional),	EtherNet/IP (optional)				
			TMflow (flo	wchart), TMsc	cript (script ba	sed), TMcraf	t (developme	nt program)			
				ISO 13	849-1, ISO 10	218-1, ISO/TS	15066				
					CE, SEMI S	2 (optional)					
					Al & Rob	ot Vision					
	Classificati	on, Object De	etection, Segn	nentation, An	omaly Detect	ion, AI OCR					
		Position	ning, 1D/2D Ba	arcode Readir	ng, OCR,						
		Defect Dete	ection, Measu	rement, Asser	mbly Check				A.I	/A	
			2D Positionin	ıg: 0.1 mm * ⁽¹⁾					N,	(n	
	TM Landm	ark 3D positio	oning (the wor	king point is	located 100/2	00/300mm					
		away from	the landmark): 0.24/ 0.53/	1.00 mm *(1)						
	Auto-focuse		a with 5M res			100 mm - 00					

^{*(1)} The data in this table are measured by TM laboratory and the working distance is 100mm. It should be noted that in practical applications, the relevant values may be different due to factors such as the on-site ambient light source, object characteristics, and vision programming methods that will affect the change in accuracy.

Support Maximum 2× GigE 2D cameras or 1× GigE 2D Camera + 1× 3D Camera *12)

^{*(2)} Refer to the official website of TM Plug&Play for camera models compatible to TM Robot.

^{*(2)} Refer to the official website of TM Plug&Play for camera models compatible to TM Robot.

Software Specification



Software Requirements							
TM AI+ Trainer Software ve	rsion Ver. 2.18 or above						
Hardware Requiremen	ts						
Operating System	Ubuntu 22.04 *(1)						
CPU	7th Generation Intel® Core™ i7 Processors or above						
RAM	32 GB or above						
Graphics Cards	Only support NVIDIA Turing and Ampere micro-architectures GPU*(2)*(3) Recommendation: NVIDIA GeForce RTX 30 series (3060 12GB or above) NVIDIA RTX professional GPUs (A4000 16GB or above)						
Storage	2TB or above (SSD Recommended)						
Communication Interface	Ethernet						
Language Support	EN, TW, CN, DE, ES, FR, JP, KO, PT, TH, VI						

- *(1) TM AI+ Trainer cannot be installed in a virtual environment on a personal computer, such as VirtualBox.
- *(2) Only NVIDIA GPUs are supported; GPUs from other manufacturers like AMD and Intel are not compatible.
- *(3) NVIDIA GPUs based on other micro-architectures, such as the GeForce RTX 40 series (Ada Lovelace architecture), are also not supported.

TM Image Manager Installation Requirements



Software Requirements						
TMflow Software Version		Ver. 2.18 or above				
Hardware Requiremen	its					
Operating System	Ubuntu 22.04 *(1) *(2)					
CPU	Gen 7 intel i7 or above					
RAM	32 GB	22 GB or above				
Storage	SSD 2TB-8TB					
Communication Interface	Ethernet					
Language Support	EN, TW, CN, JP, KO, TH					
Remark	Supports up to 10 TM AI Cobots and AI+ AOI Edges for continuous, simultaneous image transmission					

- *(1) Image Manager is not allowed to be installed on the virtual environment of personal computer, like VirtualBox.
- *(2) Please verify if the computer hardware supports Ubuntu 22.04 LTS 64.
- *(3) When more than 10 connections are established with simultaneous image transmissions, users should assess the potential risks of system overload.

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